

Konfigurierbare Systemsoftware (KSS)

VL 1 – Einführung

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Verteilte Systeme und Betriebssysteme

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SS 16 – 2016-04-11

http://www4.informatik.uni-erlangen.de/Lehre/SS16/V_KSS



The Operating System – A Swiss Army Knife?

Commodity operating systems provide a rich set of features to be prepared for all kinds of applications and contingencies:

- Malicious or erroneous applications
 - preemptive scheduling, address space separation, disk quotas
- Multi-user operation
 - authentication, access validation and auditing
- Multi-threaded and interacting applications
 - Threads, semaphores, pipes, sockets
- Many/large concurrently running applications
 - virtual memory, swapping, working sets



Agenda

- 1.1 Commodity Operating Systems Today
- 1.2 Reality Check: Granularity
- 1.3 The Domain of Embedded Systems
- 1.4 About KSS
- 1.5 KSS — Organization
- 1.6 References



The Operating System – A Swiss Army Knife?

One size fits all?

→ Variability

“ Clearly, the operating system design must be strongly influenced by the type of use for which the machine is intended. Unfortunately it is often the case with ‘general purpose machines’ that the type of use cannot be easily identified; a common criticism of many systems is that in attempting to be all things to all men they wind up being **totally satisfactory to no-one. ”**

Lister and Eager 1993: *Fundamentals of Operating Systems* [4]



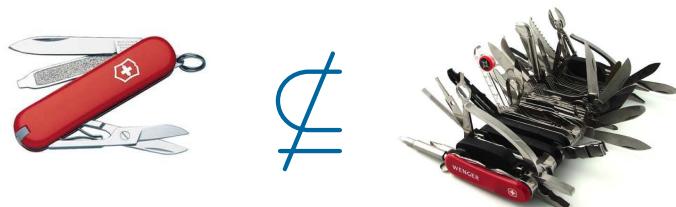
The Operating System – A Swiss Army Knife?

Big is beautiful?

→ Granularity

“ Some applications may require only a subset of services or features that other applications need. These ‘less demanding’ applications should **not be forced to pay for the resources consumed by unneeded features.** ”

Parnas 1979: “Designing Software for Ease of Extension and Contraction” [8]



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Variability and Granularity

Variability

(Definition 1)

Variability of system software is the property that denotes the *range* of functional requirements that can be fulfilled by it.

Granularity

(Definition 2)

Granularity of system software is the property that denotes the *resolution* of which requirements can be fulfilled by it, in the sense that requirements are fulfilled but not overfulfilled.

- Can general purpose (GP) systems fulfill these demands?
- Reality check – a small study with `printf()` from `glibc`:
(Analogy: GP operating system ↔ GP library ↔ GP function)

```
int main() {  
    printf( "Hello World\n");  
}
```



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Reality Check: Granularity

- The setup:

```
> uname -a  
Linux faui48a 2.6.32-5-amd64 #1 SMP Mon Oct 3 05:45:56 UTC 2011 x86_64 GNU/Linux  
> gcc -dumpversion  
4.4.5
```

- Experiment 1: `printf()`

```
> echo 'main(){printf("Hello World\n");}' | gcc -xc - -w -Os -static -o hello1  
> ./hello1  
Hello World  
> size hello1  
text     data     bss     dec     hex filename  
508723      1928     7052   517703  7e647 hello1
```

512 KiB!

- Maybe the general-purpose `printf()` is just too powerful?
 - supports many data types, formatting rules, ...
 - implementation requires a complex parser for the format string
- Let's try the much more specialized `puts()`!

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Reality Check: Granularity (Cont'd)

Experiment 2: puts()

```
> echo 'main(){puts("Hello World");}' | gcc -xc - -Os -w -static -o hello2
> ./hello2
Hello World
> size hello2
  text    data     bss     dec   hex filename
508723    1928   7052  517703  7e647 hello2
```

512 KiB!

- That didn't help much!
- Maybe puts() is yet too powerful?
 - buffered IO, streams
- Let's work directly with the OS file handle!



Reality Check: Granularity (Cont'd)

Experiment 3: write()

```
> echo '_start(){write(1, "Hello World\n", 13);_exit(0);}' | gcc -xc - -Os -w
-static -nostartfiles -o hello3
> size hello3
  text    data     bss     dec   hex filename
508138    1928   7052  517118  7e3fe hello3
```

0.5 KiB :-|

but segfault :-(|

- Even a simple write() cannot be issued without the complete initialization.
- Last resort: invoke the syscall directly!

Experiment 6: SYS_write()

```
> echo '_start(){syscall(4, 1, "Hello World\n", 13);_exit(0);}' | gcc -xc - -Os
-w -static -nostartfiles -o hello6
> size hello6
  text    data     bss     dec   hex filename
293      0       4    297    129 hello6
> ./hello6
Hello World
```

0.25 KiB :-)



Reality Check: Granularity (Cont'd)

Experiment 3: write()

```
> echo 'main(){write(1, "Hello World\n", 13);}' | gcc -xc - -Os -w -static
-o hello3
> ./hello3
Hello World
> size hello3
  text    data     bss     dec   hex filename
508138    1928   7052  517118  7e3fe hello3
```

512 KiB!

- 517703 compared to 517118 – a net saving of 585 bytes (0.1%) :-)

Experiment 4: empty program

```
> echo 'main()' | gcc -xc - -Os -w -static -o hello4
> size hello4
  text    data     bss     dec   hex filename
508074    1928   7052  517054  7e3be hello4
```

Hm...

- objdump -D --reloc hello4 | grep printf | wc -l yields still 2611 matches!
- It's the startup code!



Reality Check: Lessons Learned

297 ←→ 517703 Bytes!

On Linux/glibc, a simple "Hello World" application takes 1750 times more memory than necessary!

However, is this a problem?

- The glibc has been designed for a "standard case"
 - Large, multithreaded, IO-intensive UNIX application
 - Assumption: every program uses malloc(), printf(), ...
- Variability has been traded for Granularity

Every Program?

“I know of no feature that is always needed. When we say that two functions are almost always used together, we should remember that “almost” is a euphemism for “not”. ”

Parnas 1979: "Designing Software for Ease of Extension and Contraction" [8]



Reality Check: Lessons Learned

297 ↔ 517703 Bytes!

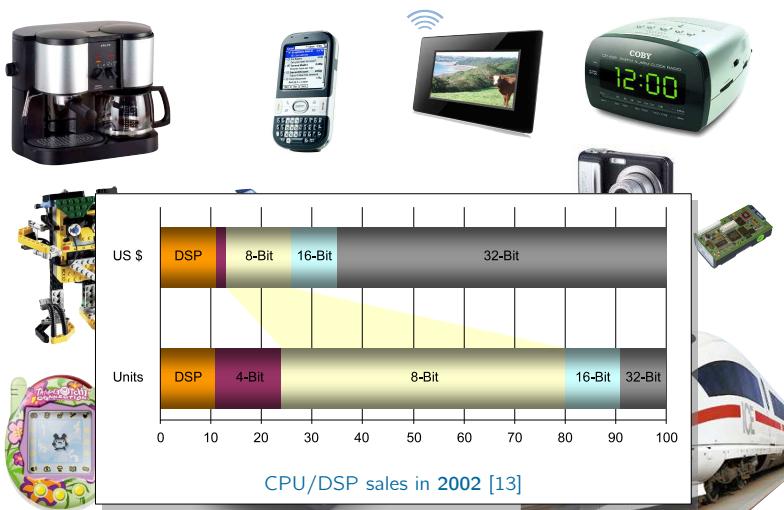
On Linux/glibc, a simple "Hello World" application takes **1750 times** more memory than necessary!

- However, is this a problem?
 - The glibc has been designed for a "standard case"
 - Large, multithreaded, IO-intensive UNIX application
 - Assumption: every program uses `malloc()`, `printf()`, ...
 - Variability has been traded for Granularity
- Assumption: The GP operating system will compensate for it...
 - Virtual memory ↵ memory is not an issue
(but is that a reason to waste it?)
 - Shared libraries ↵ memory is actually shared between processes
(unless we relocate the symbols, e.g., for address-space randomization...)

What about other domains?



A Different Domain: Embedded Systems



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The ATmega µC Family (8-Bit)

Type	Flash	SRAM	IO	Timer 8/16	UART	SPI	ADC	PWM	EUR
ATTINY13	1 KiB	64 B	6	1/-	-	-	1*4	-	0.86
ATTINY2313	2 KiB	128 B	18	1/1	-	1	-	-	0.99
ATMEGA48	4 KiB	512 B	23	2/1	1	1	8*10	6	1.40
ATMEGA16	16 KiB	1024 B	32	2/1	1	1	8*10	4	2.05
ATMEGA32	32 KiB	2048 B	32	2/1	1	1	8*10	4	3.65
ATMEGA64	64 KiB	4096 B	53	2/2	2	1	8*10	8	5.70
ATMEGA128	128 KiB	4096 B	53	2/2	2	1	8*10	8	7.35
ATMEGA256	256 KiB	8192 B	86	2/2	4	1	16*10	16	8.99

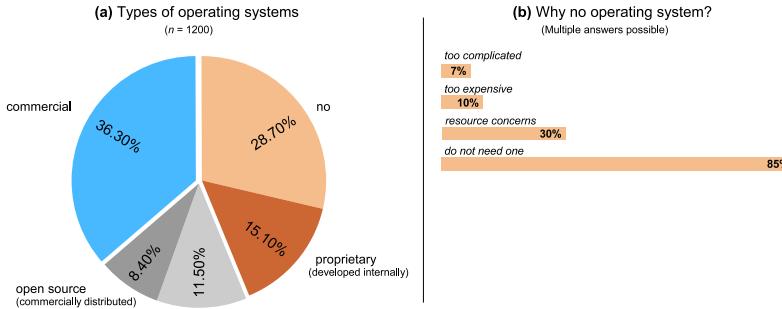
Prices and features of ATmega variants (excerpt, Reichelt April 2015)

Limited Resources

- Flash is limited, RAM is extremely limited
- A **few bytes** can have a **massive impact** on per-unit **costs**
 - ↝ The "glibc approach" is **doomed to fail!**



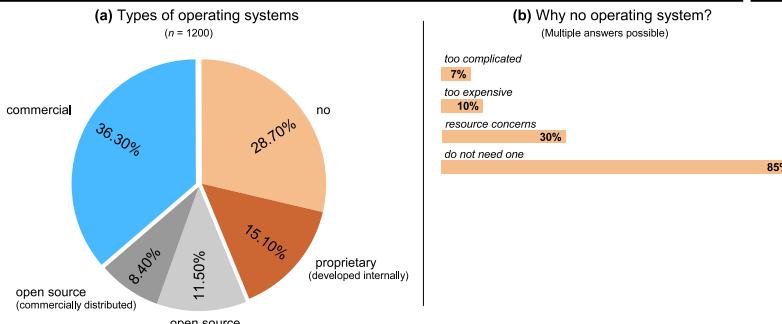
The Role of the Operating System



Operating systems (not) employed in embedded-system projects in 2006 [12]



The Role of the Operating System



Operating systems (not) employed in embedded-system projects in 2006 [12]

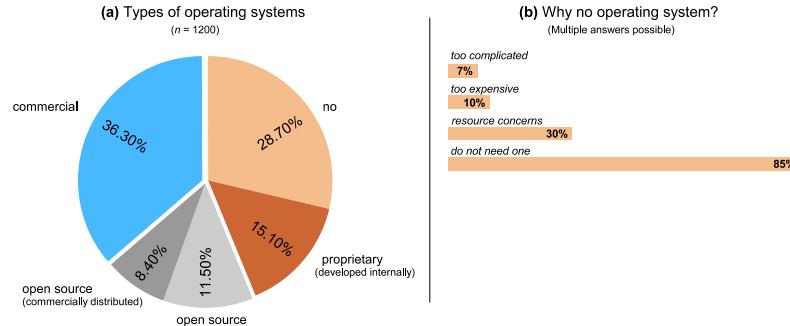
Rest spreads over **hundreds of different** operating systems!

..., C{51, 166, 251}, CiAO, CMX RTOS, Contiki, C-Smart/Raven, eCos, eRTOS, Embos, Ercos, Euros Plus, FreeRTOS, Hi Ross, HyNet-OS, LynxOS, MicroX/OS-II, Nucleus, OS-9, OSE, OSEK {Flex, Turbo, Plus}, OSEKtime, Precise/MQX, Precise/RTCS, proOSEK, pSOS, PURE, PXROS, QNX, Realos, RTMOSxx, Real Time Architect, RTA, RTX{51, 166, 251}, RTXC, Softone, SSXS RTOS, ThreadX, TinyOS, Tresos, VRTX, VxWorks, ...

~ The “glibc approach” (one size fits all) **does not work!**



The Role of the Operating System



Operating systems (not) employed in embedded-system projects in 2006 [12]

> 40% of all projects use “in house” OS functionality!

Wide-spread fear of the resource overhead of GP operating systems

- OS functionality is developed “side-by-side” with the applications
- This leads to very high “hidden” development costs

[14]

Between a Rock and a Hard Place...

functional and nonfunctional requirements



functional and nonfunctional properties

tasks
sockets
file system
...
event latency
safety
...

ISA
IRQ handling
MMU / MPU
...
cache size
coherence
IRQ latency
...

...

Between a Rock and a Hard Place...

functional and nonfunctional requirements

- High variety of functional and nonfunctional application requirements
- High variety of hardware platforms
- High per-unit cost pressure
- ~ System software has to be **tailored** for each concrete application



tasks
sockets
file system
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event latency
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Between a Rock and a Hard Place...

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IRQ handling
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...



Customizing / Tailoring

Customizing/Tailoring

(Definition 3)

Customizing or tailoring is the activity of modifying existing system software in order to fulfill the requirements of some particular application.

This calls for **granularity** and **variability**!



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What to do?

297 \longleftrightarrow 517703 Bytes!

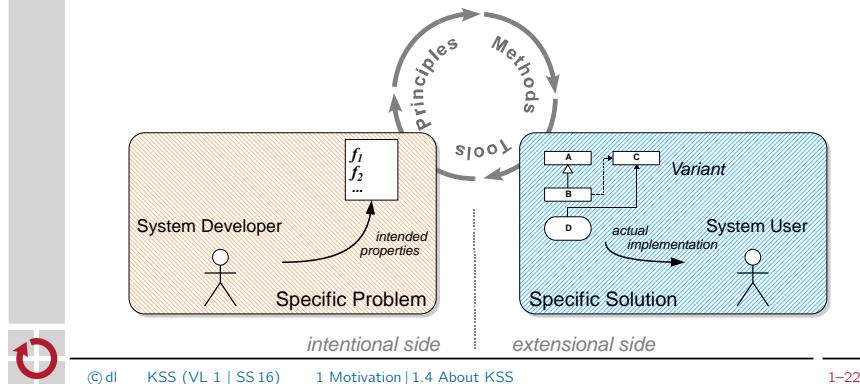
Why?

On Linux/glibc, a simple "Hello World" application takes **1750 times** more memory than necessary!

- Reason: software structure
 - Trade-off between **reuse \longleftrightarrow coupling**
~ by extensive internal reuse, glibc has become an all-or-nothing blob
- Reason: software interface
 - C standard defines `printf()` as a swiss army knife [3, §7.19.6]
~ `printf()` has become a "god method" [1]
- Reason: language and tool chain
 - Compiler/linker work on the granularity of symbols or even object files
~ dead code is not effectively eliminated



Individually Developed Software Product



What to do?

297 \longleftrightarrow 517703 Bytes!

Why?

On Linux/glibc, a simple "Hello World" application takes **1750 times** more memory than necessary!

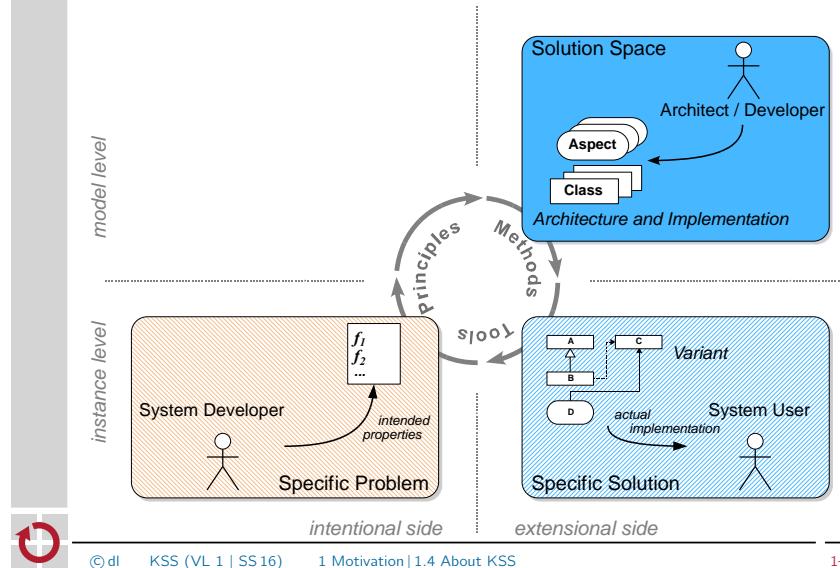
~ Konfigurierbare Systemsoftware – KSS

Throughout the software development cycle, **variability** and **granularity** have to be considered as primary design goals from the very beginning!

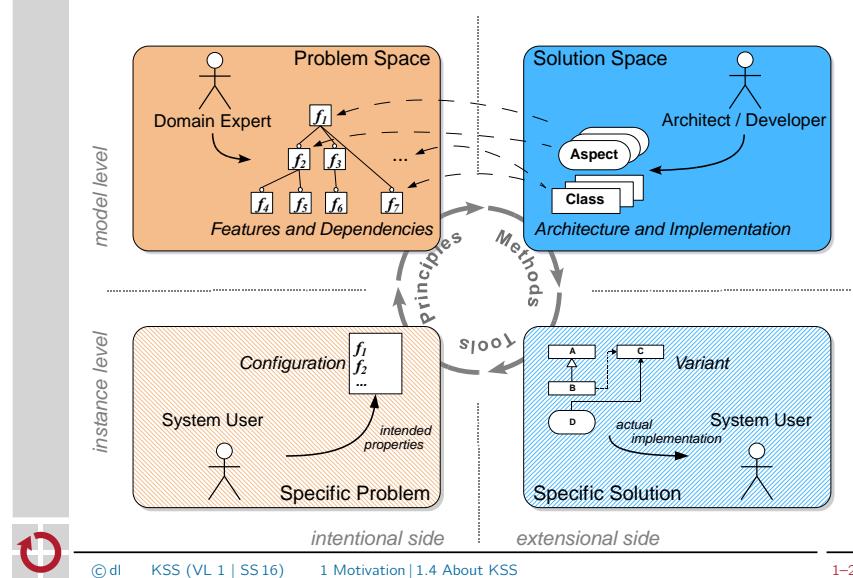
In KSS you will learn about **principles, methods, and tools** to achieve this.



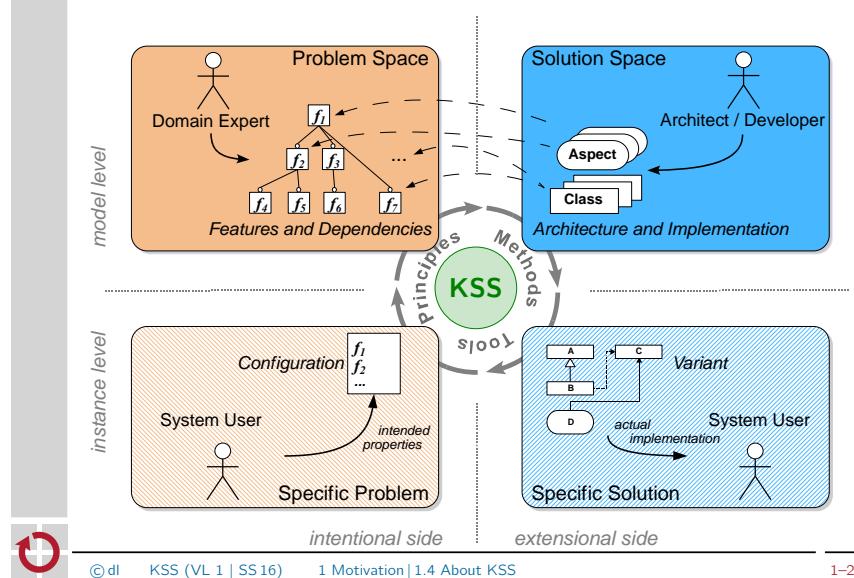
Software Product Derived from Reusable Assets



Configurable Software – Software Product Line



Configurable Software – Software Product Line



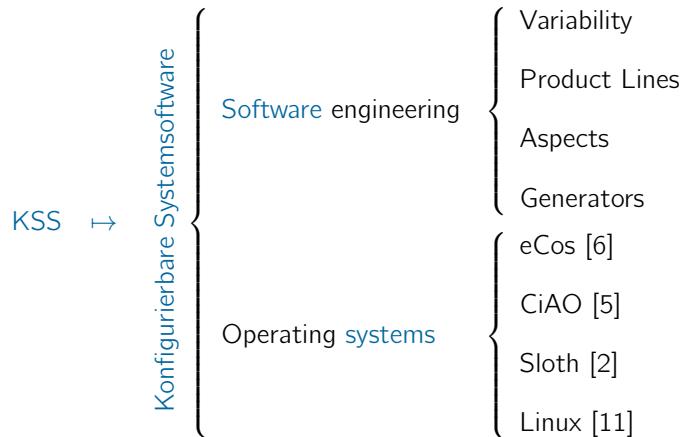
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 - Objectives
 - Einordnung
 - Semesterplanung
- 1.6 References

Learning Objectives

- **Improve** your understanding of the design and development of low-level system software
 - Starting point: "Betriebssysteme" [BS]
 - Focus: Static configuration and tailoring
- **Expand** your knowledge by new software engineering methods and language techniques for configurable system software
 - Software families and software product lines [7]
 - Aspect-oriented and generative programming in C/C++ [10]
- **Apply** these techniques in the context of current operating-system research projects
 - CiAO, SLOTH, VAMOS, DanceOS [2, 5, 9, 11]
 - Get prepared for a master thesis or project in the field!

Topics



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Organisation: Systemsoftwaretechnik (SST)

- Modul Systemsoftwaretechnik (SST) **7.5 ECTS**
 - ① Vorlesung Betriebssystemtechnik (BST) 2.5
 - Mo 14–16
 - 12–14 Vorlesungstermine
 - ② Übungen zu Betriebssystemtechnik (BST-Ü) 2.5
 - Mi 10–12
 - 10 Übungstermine
 - ③ Vorlesung und Übung **Konfigurierbare Systemsoftware (KSS)** 2.5
 - Mo 12–14
 - 7 Vorlesungstermine, 1–2 Übungsaufgaben
 - Übung integriert in BST-Übung / Rechnerübung
- ↗ KSS kann **nur zusammen mit BST** belegt werden!
 - Es gibt keine 2.5 ECTS Module...
 - Wenn Bedarf besteht, wird KSS auf 5 ECTS erweitert

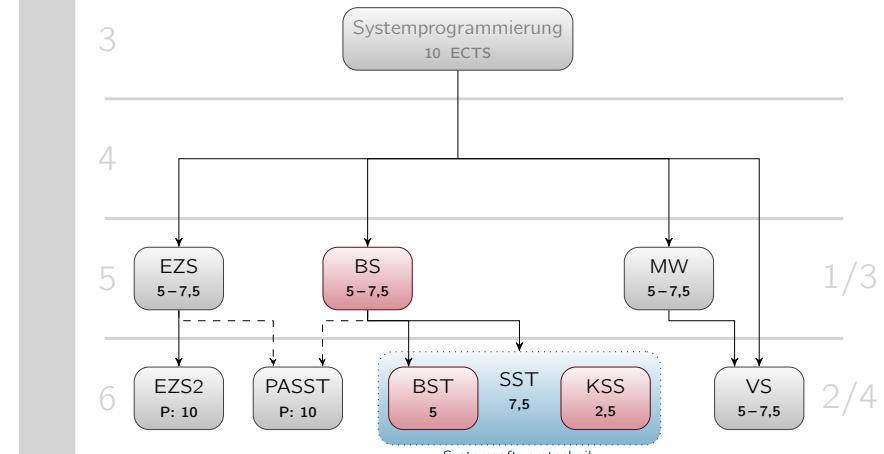


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KSS – Einordnung

(Bachelor/Master)



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Organisation: Beteiligte

Vorlesung



Daniel Lohmann

Übung



Christian Dietrich Valentin Rothberg

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Semesterplanung

KW	Mo	Di	Mi	Do	Fr	Themen
16	13.04 20.04	14.04 21.04	15.04 22.04	16.04 23.04	17.04 24.04	BST VL1: Organization und Einleitung KSS VL1: Introduction, Motivation and Concept
17						BST VL2: Systemaufbau
18	27.04 KSS VL2	28.04 TÜ BST A1	29.04 KSS VL3	30.04 01.05		KSS VL2: Software Families and Software Product Lines BST VL3: Aspect-Oriented Programming, AspectC++ KSS VL3: Aspect-Oriented Programming, AspectC++
19	04.05 KSS VL4	05.05 TU KSS A1	06.05 Abgabe BST A1	07.05 08.05		KSS VL4: Aspect-Aware Design, CiAO BST VL4: Hierarchien
20	11.05 KSS VL5	12.05 TÜ BST A2	13.05 Himmelf.	14.05 21.05	15.05 22.05	KSS VL5: Variability in the Large, VAMOS BST VL5: Generative Programming, Sloth KSS VL5: Generative Programming, Sloth
21	25.05 Pfingsten/Berg	26.05 01.06	27.05 02.06	28.05 03.06	29.05 04.06	BST VL7: Conclusion, Summary BST VL8: Adressraummodelle
22						
23		BST VL7 (Rechnerübung)				BST VL7: Sprachbasierung
24	08.06 TÜ BST A3	09.06 Abgabe BST A2	10.06 01.07	11.06 02.07	12.06 03.07	BST VL8: Interprozesskommunikation
25	15.06 BST VL9	16.06 23.06	17.06 24.06	18.06 25.06	19.06 26.06	BST VL9: Kommunikationsabstraktionen BST VL10: Mitbenutzung
26	22.06 BST VL10	23.06 30.06	24.06 01.07	25.06 02.07	26.06 03.07	BST VL11: Bindelader
27	29.06 BST VL11	30.06 07.07	01.07 08.07	02.07 09.07	03.07 10.07	BST VL12: Nachlese
28	06.07 BST VL12	07.07 13.07	08.07 14.07	09.07 15.07	10.07 16.07	Abgabe BST A3
29						

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