

Konfigurierbare Systemsoftware (KSS)

VL 2 – Software Product Lines

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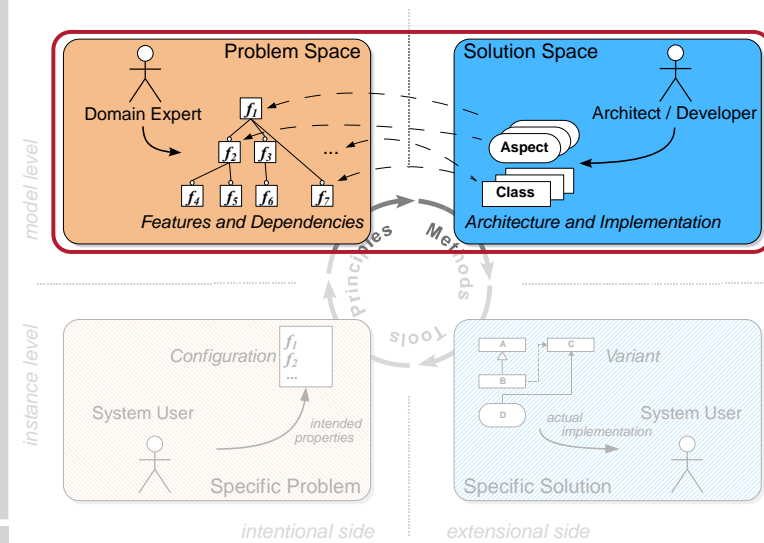
SS 12 – 2012-05-09

http://www4.informatik.uni-erlangen.de/Lehre/SS12/V_KSS

Agenda

- 2.1 Motivation: The Quest for Variety
- 2.2 Introduction: Software Product Lines
- 2.3 Case Study: i4Weathermon
- 2.4 Problem Space
- 2.5 Solution Space
- 2.6 References

About this Lecture



Agenda

- 2.1 Motivation: The Quest for Variety
 - Model Car Industry
 - Challenges
- 2.2 Introduction: Software Product Lines
- 2.3 Case Study: i4Weathermon
- 2.4 Problem Space
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Model Car Industry: Variety of an BMW X3



- Roof interior: **90000** variants available
- Car door: **3000** variants available
- Rear axle: **324** variants available

“Varianten sind ein wesentlicher Hebel für das Unternehmensergebnis”
Franz Decker (BMW Group)

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Model Car Industry: Variety Increase

■ In the 1980s: little variety

- Option to choose series and maybe a few extras (tape deck, roof rack)
- A **single variant** (Audi 80, 1.3l, 55 PS) accounted for **40 percent** of Audi's total revenue

■ Twenty years later: built-to-order

- Audi: **10^{20}** possible variants
- BMW: **10^{32}** possible variants
- At average there are 1.1 equal instances of an Audi A8 on the street

↳ **Product lines** with fully automated assembly

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optional, independent
33 features



one individual variant
for each human being


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optional, independent
320 features

more variants than
atoms in the universe!

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Typical Configurable Operating Systems...



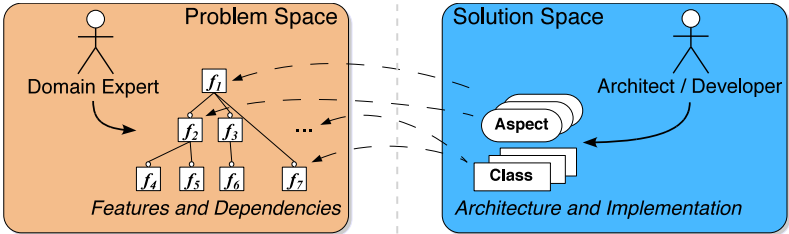
1250 features



11000 features

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Challenges



- 1 How to **identify** the actually desired variability?
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Agenda

- 2.1 Motivation: The Quest for Variety
- 2.2 Introduction: Software Product Lines
 - Terms and Definitions
 - SPL Development Process
 - Our Understanding of SPLs
- 2.3 Case Study: i4Weathermon
- 2.4 Problem Space
- 2.5 Solution Space
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Definition: (Software) Product Line, Feature

Product Line (Withey) (Definition 1)

“ A **product line** is a group of products sharing a common, managed set of **features** that satisfy the specific needs of a selected **market**. ”

Withey 1996: *Investment Analysis of Software Assets for Product Lines* [12]

Software Product Line (SEI) (Definition 2)

“ A **software product line (SPL)** is a set of software-intensive systems that share a common, managed set of **features** satisfying the specific needs of a particular **market** segment or mission and that are developed from a common set of core assets in a prescribed way. ”

Northrop and Clements 2001: *Software Product Lines: Practices and Patterns* [8]

Remarkable:
SPLs are not motivated by **technical** similarity of the products, but by **feature** similarity wrt a certain **market**

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Definition: (Software) Product Line, Feature

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Feature (Czarnecki / Eisenecker) (Definition 3)

“ A distinguishable characteristic of a concept [...] that is relevant to some stakeholder of the concept. ”

Czarnecki and Eisenecker 2000: *Generative Programming, Methods, Tools and Applications* [3, p. 38]

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The Emperors New Clothes?

Program Family (Definition 4)

“ Program families are defined [...] as sets of programs whose common properties are so extensive that it is advantageous to study the common properties of the programs before analyzing individual members. ”

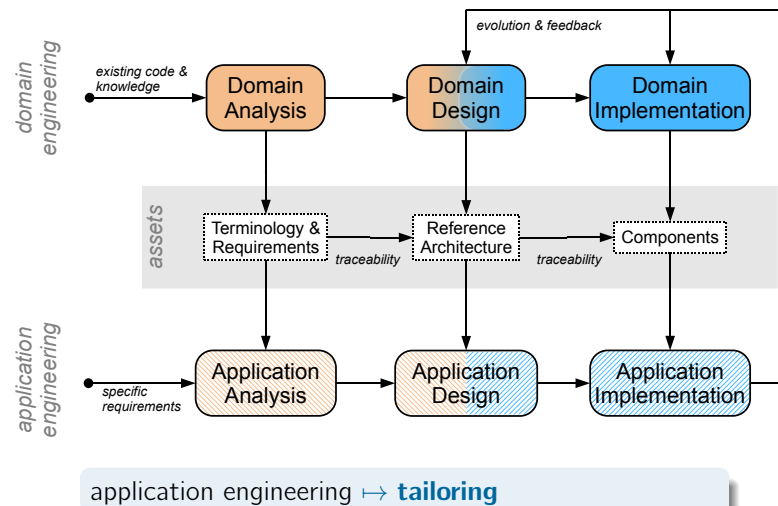
Parnas 1976: "On the Design and Development of Program Families" [10]

- Most research on operating-system *families* from the '70s would today qualify as work on software product lines [2, 4, 5, 9–11]
 - Program Family \Leftrightarrow Software Product Line
- However, according to the definitions, the viewpoint is different
 - Program family: defined by similarity between **programs** \rightarrow Solutions
 - SPL: defined by similarity between **requirements** \rightarrow Problems
- \Rightarrow A program family **implements** a software product line
- In current literature, however, both terms are used synonymously
 - Program Family \Leftrightarrow Software Product Line

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SPL Development Reference Process [1]



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Our understanding: Configurable System Software

Configurability (Definition 5)

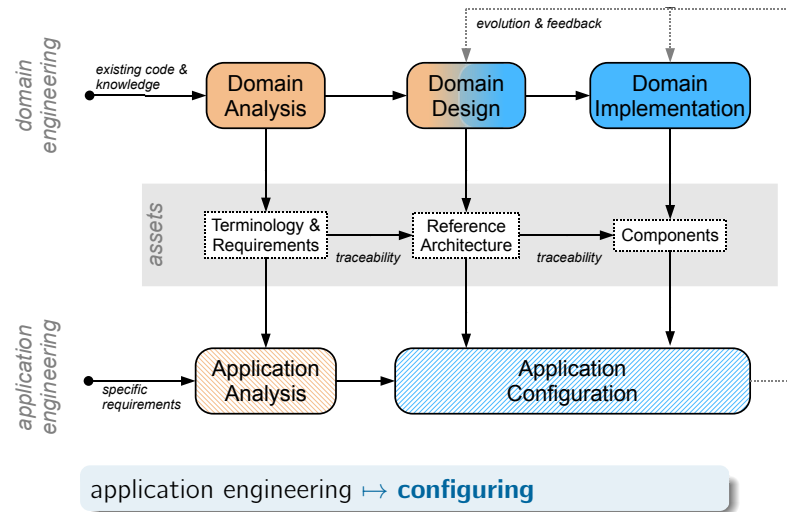
Configurability is the property that denotes the degree of pre-defined variability and granularity offered by a piece of system software via an explicit **configuration interface**.

- Common configuration interfaces
 - Text-based: **configure** script or **configure.h** file (GNU tools)
 - configuration by commenting/uncommenting of (preprocessor) flags
 - no validation, no explicit notion of feature dependencies
 - Tool-based: KConfig (Linux, busybox, CiAO, ...), ecosConfig (eCos)
 - configuration by an interactive configuration editor
 - formal model of configuration space, hierarchical features
 - implicit/explicit validation of constraints

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Configurable SPL Reference Process



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The i4WeatherMon Weather Station [7]

■ A typical embedded system

■ Several, optional sensors

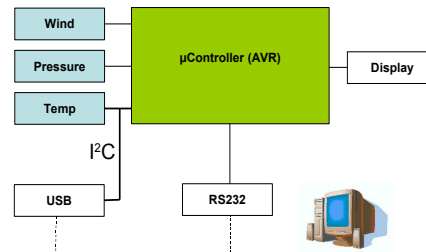
- Wind
- Air Pressure
- Temperature

■ Several, optional actuators (here: output devices)

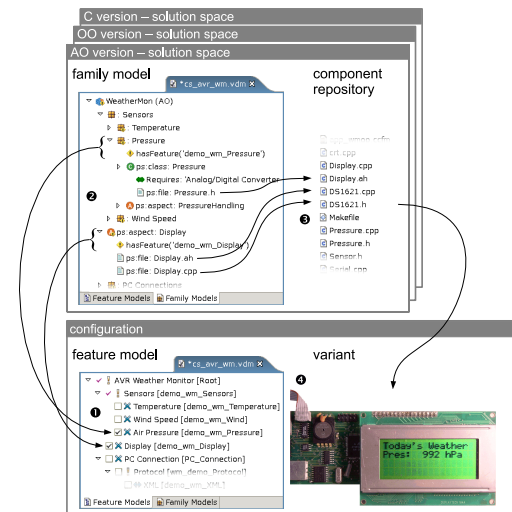
- LCD
- PC via RS232
- PC via USB

■ To be implemented as a product line

- **Barometer:** Pressure + Display
- **Thermometer:** Temperature + Display
- **Deluxe:** Temperature + Pressure + Display + PC-Connection
- **Outdoor:** <as above> + Wind
- ...



The i4WeatherMon Software Product Line [7]



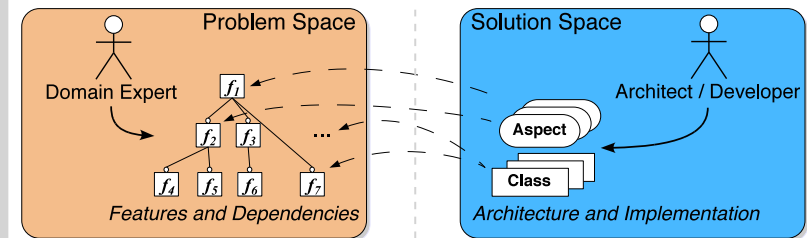
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Challenges

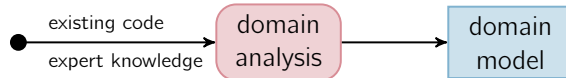


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Domain Analysis



- **Domain Scoping**
 - Selection and processing of domain knowledge
 - Restriction of diversity and variety
- **Domain Modelling**
 - Systematic evaluation of the gained knowledge
 - Development of a taxonomy

~ Domain Model (Definition 6)

“ A **domain model** is an explicit representation of the **common** and the **variable** properties of the system in a domain, the semantics of the properties and domain concepts, and the dependencies between the variable properties. ”

Czarnecki and Eisenecker 2000: *Generative Programming. Methods, Tools and Applications* [3]

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Elements of the Domain Model

- **Domain definition** specifies the scope of the domain
 - Examples and counter examples
 - Rules for inclusion/exclusion of systems or features
- **Domain glossary** defines the vocabulary of the domain
 - Naming of features and concepts
- **Concept models** describe relevant concepts of the domain
 - Formal description (e.g., by UML diagrams)
 - Textual description
 - Syntax and semantics
- **Feature models** describe the common and variable properties of domain members
 - Textual description
 - Feature diagrams

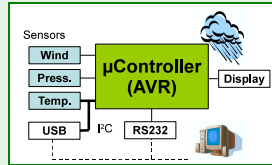
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I4WeatherMon: Domain Model (simplified)

Domain Definition: i4WeatherMon

- The domain contains software for the depicted modular hardware platform. Future version should also support new sensor and actuator types (humidity, alarm, ...).
- The externally described application scenarios **thermometer**, **barometer**, **outdoor**, ... shall be supported.
- The i4WeatherMon controller software is shipped in the flash memory of the μ C and shall not be changed after delivery.
- ...



I4WeatherMon: Domain Model (simplified)

Domain Glossary: i4WeatherMon

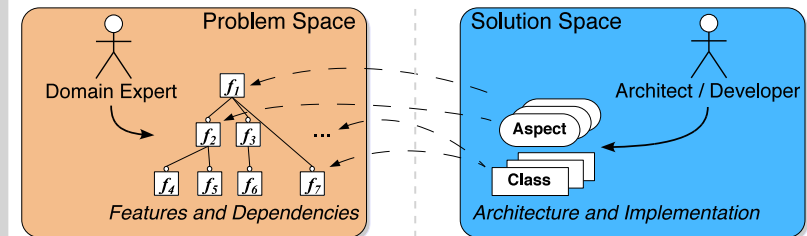
- **PC Connection:** Optional communication channel to an external PC for the sake of continuous transmission of weather data. Internally also used for debug purposes.
- **Sensor:** Part (1 or more) of the i4WeatherMon hardware that measures a particular weather parameter (such as: temperature or air pressure).
- **Actuator:** Part (1 or more) of the i4WeatherMon hardware that processes weather data (such as: LCD).
- **XML Protocol:** XML-based data scheme for the transmission of weather data over a **PC Connection**.
- ...

I4WeatherMon: Domain Model (simplified)

Concept Models: i4WeatherMon

- **XML Protocol:** The following DTD specifies the format used for data transmission over a **PC Connection**:
`<!ELEMENT weather ...> ...`
- **PC Connection** ...
- ...

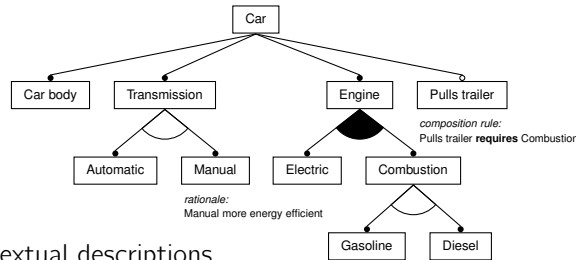
Challenges



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Feature Models

- Describe system variants by their commonalities and differences
 - Specify configurability in terms of optional and mandatory features
 - Intentional construct, independent from actual implementation
- Primary element is the **Feature Diagram**:
 - Concept (Root)
 - Features
 - Constraints
- Complemented by textual descriptions
 - Definition and rationale of each feature
 - Additional constraints, binding times, ...

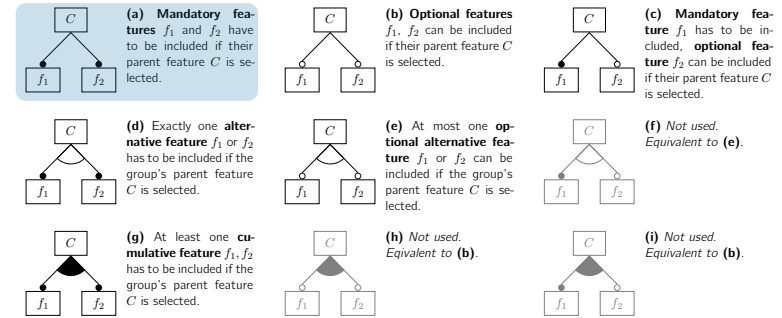
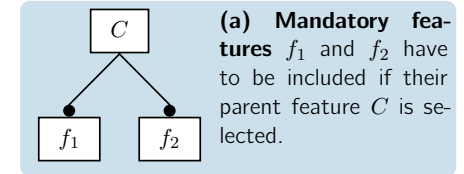


Feature Diagrams – Language

[3]

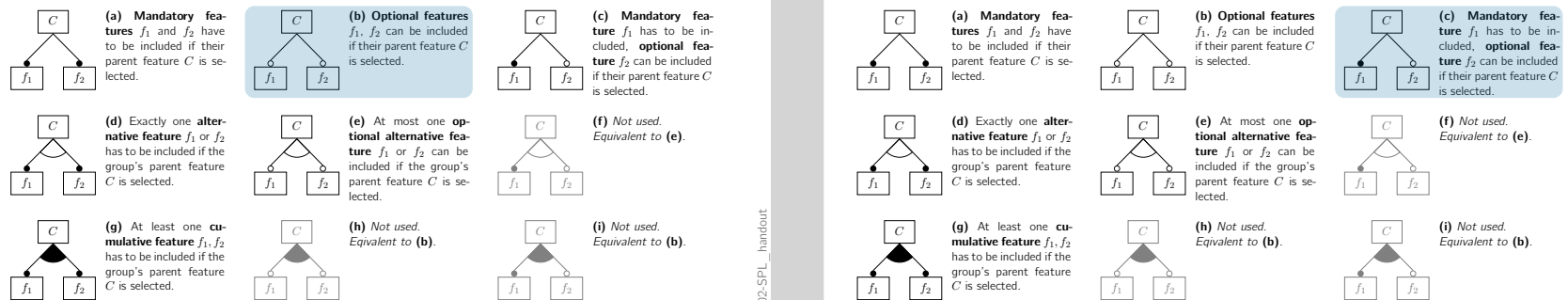
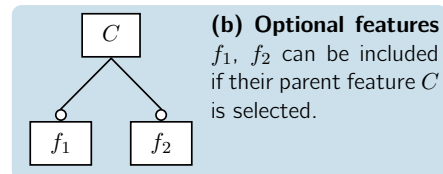
Syntactical Elements

The filled dot ● indicates a mandatory feature:
 $\mathcal{V} = \{(C, f_1, f_2)\}$



Syntactical Elements

A shallow dot ○ indicates an optional feature:
 $\mathcal{V} = \{(C), (C, f_1), (C, f_2), (C, f_1, f_2)\}$

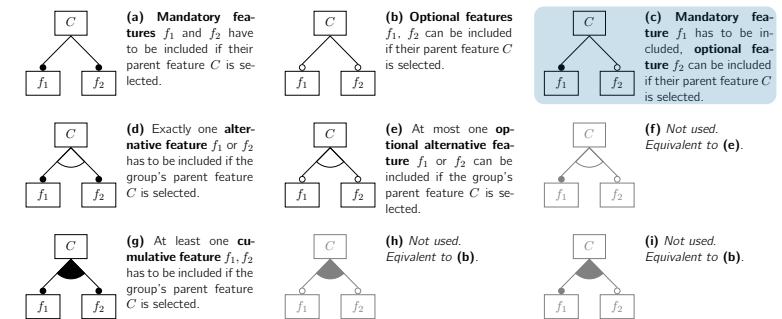
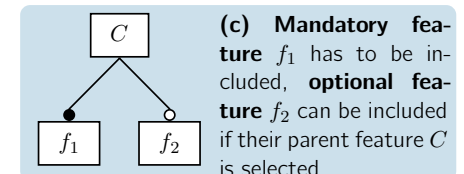


Feature Diagrams – Language

[3]

Syntactical Elements

Of course, both can be combined:
 $\mathcal{V} = \{(C, f_1), (C, f_1, f_2)\}$



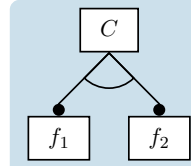
Feature Diagrams – Language

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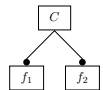
Syntactical Elements

The shallow arc \triangle depicts a group of alternative features:

$$\mathcal{V} = \{(C, f_1), (C, f_2)\}$$



(d) Exactly one **alternative feature** f_1 or f_2 has to be included if the group's parent feature C is selected.



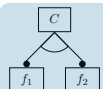
(a) **Mandatory features** f_1 and f_2 have to be included if their parent feature C is selected.



(b) **Optional features** f_1, f_2 can be included if their parent feature C is selected.



(c) **Mandatory feature** f_1 has to be included, **optional feature** f_2 can be included if their parent feature C is selected.



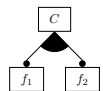
(d) Exactly one **alternative feature** f_1 or f_2 has to be included if the group's parent feature C is selected.



(e) At most one **optional alternative feature** f_1 or f_2 can be included if the group's parent feature C is selected.



(f) *Not used. Equivalent to (e).*



(g) At least one **cumulative feature** f_1, f_2 has to be included if the group's parent feature C is selected.



(h) *Not used. Equivalent to (b).*



(i) *Not used. Equivalent to (b).*

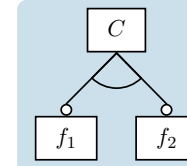
Feature Diagrams – Language

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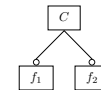
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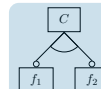
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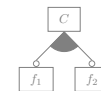
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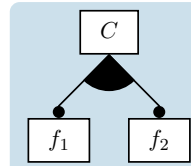
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Feature Diagrams – Language

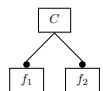
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Syntactical Elements

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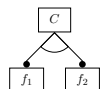
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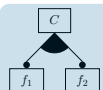
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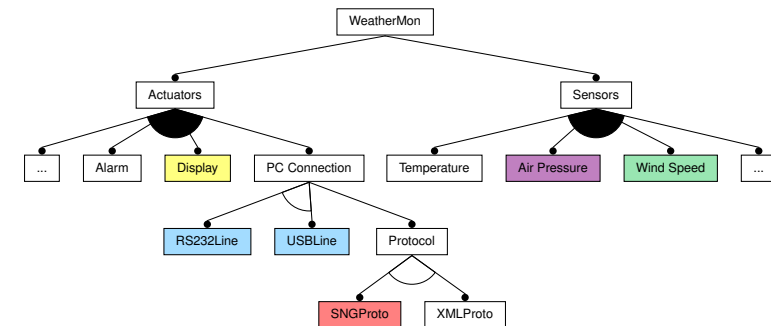


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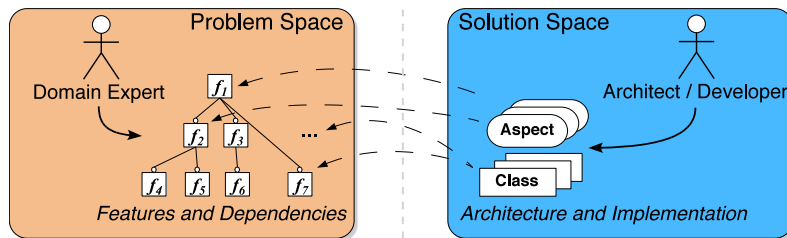


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I4WeatherMon: Feature Model



Challenges



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 - Reference Architecture
 - Implementation Techniques Overview
 - Variability Implementation with the C Preprocessor
 - Variability Implementation with OOP (C++)
 - Evaluation and Outlook
- 2.6 References

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i4WeatherMon: Reference Architecture

Functional decomposition (structure and process):

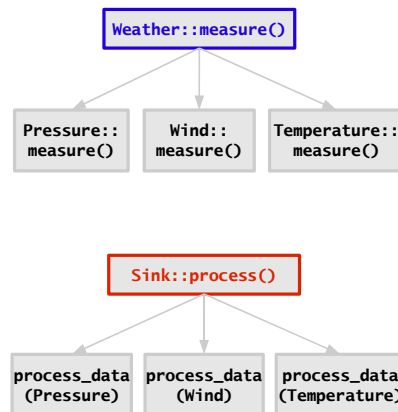
```
int main() {
    Weather data;
    Sink sink;

    while(true) {

        // aquire data
        data.measure();

        // process data
        sink.process( data );

        wait();
    }
}
```



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Implementation Techniques: Classification

- Decompositional Approaches
 -
 - Text-based filtering (untyped)
 - Preprocessors
- Compositional Approaches
 -
 - Language-based composition mechanisms (typed)
 - OOP, AOP, Templates
- Generative Approaches
 -
 - Metamodel-based generation of components (typed)
 - MDD, C++ TMP, generators

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I4WeatherMon (CPP): Implementation (Excerpt)

```

// sensor processing
inline void init_sensors() {
#ifdef cfWML_STACK
    stack_init();
#endif
#ifdef cfWML_WIND
    wind_init();
#endif
#ifdef cfWML_PRESSURE
    pressure_init();
#endif
#ifdef cfWML_TEMPERATURE
    temperature_init();
#endif
}

// sensor processing
inline void process() {
    // measure the weather data
    measure();
    // process the weather data
    process();
    // output the weather data
    output();
}

// sensor processing
inline void init_sensors() {
#ifdef cfWML_STACK
    stack_init();
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#ifdef cfWML_WIND
    wind_init();
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#ifdef cfWML_PRESSURE
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#endif
}

// sensor processing
inline void process() {
    // measure the weather data
    measure();
    // process the weather data
    process();
    // output the weather data
    output();
}
    
```

Sensor (and actuator) integration both crosscut the structure of the main program, an interaction with a mandatory feature.

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I4WeatherMon (CPP): Implementation (Excerpt)

```

inline void XMLCon.process() {
    char val[ 5 ];
    Serial::send ("<?xml version='1.0'?>\n" "<weather>\n");

#ifdef cfWML_WIND
    wind_stringval( val );
    XMLCon.data ( wind_name(), val );
#endif

#ifdef cfWML_PRESSURE
    pressure_stringval( val );
    XMLCon.data ( pressure_name(), val );
#endif

#ifdef cfWML_TEMPERATURE
    temperature_stringval( val );
    XMLCon.data ( temperature_name(), val );
#endif

#ifdef cfWML_STACK
    stack_stringval( val );
    XMLCon.data ( stack_name(), val );
#endif

    Serial::send ("</weather>\n");
}
    
```

Sensor integration also crosscuts actuator code, an interaction between optional features!

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I4WeatherMon (CPP): Evaluation

General

- 1 Separation of concerns (SoC) ✗
- 2 Resource thriftiness ✓

Operational

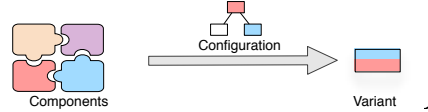
- 3 Granularity (✓)
 - Components implement only the functionality of a single feature, but contain integration code for other optional features.
- 4 Economy ✓
 - All features is bound at compile time.
- 5 Pluggability ✗
 - Sensor integration crosscuts main program and actuator implementation.
- 6 Extensibility ✗
 - New actuators require extension of main program.
 - New sensors require extension of main program and existing actuators.

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Implementation Techniques: OOP

Compositional Approaches



- Language-based composition mechanisms (typed)
- OOP, AOP, Templates

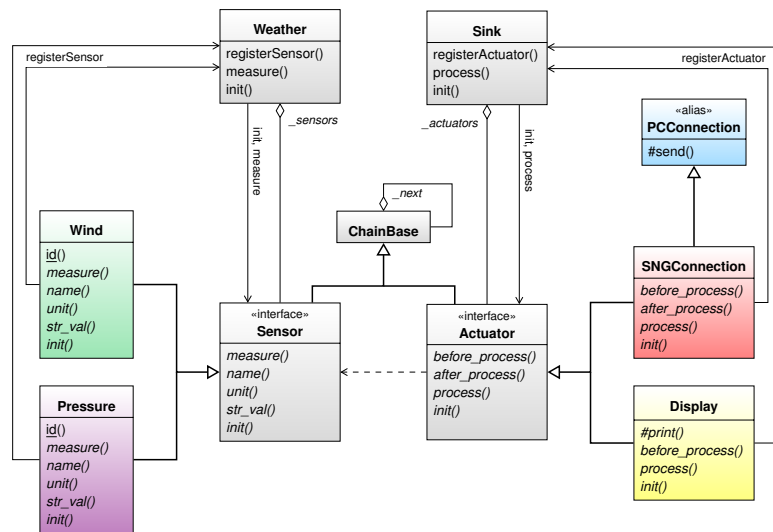
Object-oriented programming languages provide means for loose coupling by generalization and OO design patterns

- Interfaces
 - ~> type substitutability (optional/alternative features)
- Observer-Pattern
 - ~> quantification (cumulative feature groups)
- Implicit code execution by global instance construction
 - ~> self integration (optional features)

02-SPL_handout



I4WeatherMon (OOP): Design (Excerpt)



I4WeatherMon (OOP): Evaluation

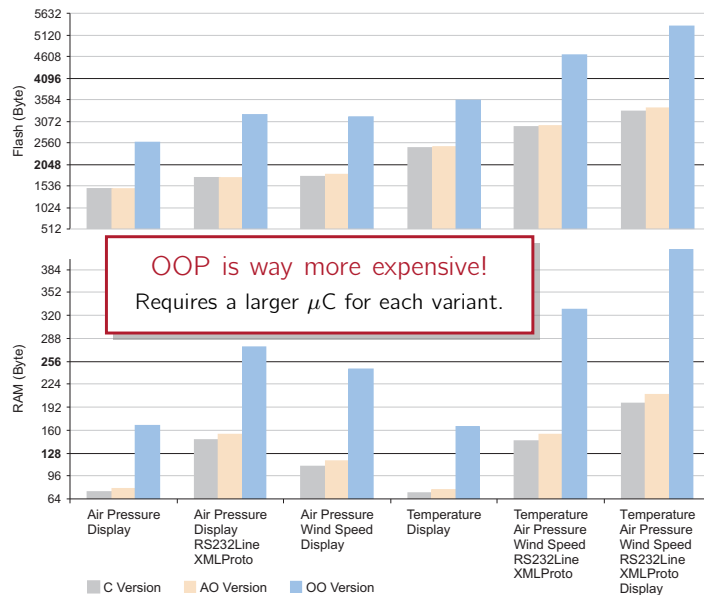
General

- 1 Separation of concerns (SoC) ✓
- 2 Resource thriftiness ?

Operational

- 3 Granularity ✓
 - Every component is either a base class or implements functionality of a single feature only.
- 4 Economy (✓)
 - Run-time binding and run-time type information is used only where necessary to achieve SoC.
- 5 Pluggability ✓
 - Sensors and actuators integrate themselves by design patterns and global instance construction.
- 6 Extensibility ✓
 - "Plug & Play" of sensor and actuator implementations.

I4WeatherMon: CPP vs. OOP – Footprint



Legend: C Version (Grey), AO Version (Orange), OO Version (Blue)

I4WeatherMon: CPP vs. OOP – Footprint

variant	version	text	data	bss	stack	= flash	= RAM	time (ms)
Air Pressure, Display	C	1392	30	7	34	1422	71	1.21
	AO	1430	30	10	38	1460	78	1.21
	OO	2460	100	22	44	2560	166	1.29
Air Pressure, Display, RS232Line, XMLProto	C	1578	104	7	34	1682	145	60.40
	AO	1622	104	12	38	1726	154	59.20
	OO	3008	206	26	44	3214	276	60.80
Air Pressure, Wind Speed, Display	C	1686	38	14	55	1724	107	2.96
	AO	1748	38	18	61	1786	117	2.96
	OO	3020	146	33	65	3166	244	3.08
Temperature, Display	C	2378	28	8	34	2406	70	1.74
	AO	2416	28	11	38	2444	77	1.73
	OO	3464	98	23	44	3562	165	1.82
Temperature, Wind Speed, Air Pressure, RS232Line, XMLProto	C	2804	90	17	35	2894	142	76.40
	AO	2858	90	23	41	2948	154	76.40
	OO	4388	248	39	41	4636	328	76.40
Temperature, Wind Speed, Air Pressure, RS232Line, XMLProto, Display	C	3148	122	17	57	3270	196	79.60
	AO	3262	122	24	63	3384	209	77.60
	OO	5008	300	44	67	5308	411	80.00

Implementation Techniques: Summary

- CPP: minimal hardware costs – but no separation of concerns
- OOP: separation of concerns – but high hardware costs
- OOP cost drivers
 - Late binding of functions (virtual functions)
 - Calls cannot be inlined (↪ *memory* overhead for small methods)
 - Virtual function tables
 - Compiler always generates constructors (for vtable initialization)
 - Dead code elimination less effective
 - Dynamic data structures
 - Static instance construction
 - Generation of additional initialization code
 - Generation of a global constructor table
 - Additional startup-code required

Root of the problem:

With OOP we have to use **dynamic** language concepts to achieve loose coupling of **static** decisions.
↪ **AOP** as an alternative.



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